

Computational Models – Lecture 12¹

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June 2017

¹Based on foils by Iftach Haitner, Benny Chor, Maurice Herlihy.

Talk Outline

- ▶ Reminder: DTIME, NTIME
 - ▶ Verifiability
 - ▶ The class $co-NP$
 - ▶ Reductions and NP-completeness
 - ▶ Satisfiability and the Cook-Levin Theorem
 - ▶ Additional NP languages
- Sipser's book, 7.4–7.5

Section 1

Time Classes

Reminder – time

Definition 1 (Deterministic Time)

Let M be a **deterministic** TM, and let $t : \mathbb{N} \rightarrow \mathbb{N}$. We say that M runs in time $t(n)$ if, for **every** input x of length n , the number of steps that $M(x)$ uses is **at most** $t(n)$.

Note that $t(n)$ running time is also required for strings **not** in L .

Definition 2 (Nondeterministic Time)

A **non-deterministic** TM N runs in time $f(n)$, where $f : \mathbb{N} \rightarrow \mathbb{N}$ if, for **every** input x of length n , the **maximum** number of steps that N uses on **any branch** of its computation tree on x is **at most** $f(n)$.

Notice that also **non-accepting** branches must **reject** within $f(n)$ many steps.

Note that this is the **depth** of the computation tree, not the **size** of the tree.

The Classes \mathcal{P} and \mathcal{NP}

Definition 3 (DTIME)

For $t: \mathbb{N} \rightarrow \mathbb{N}$, let $\text{DTIME}(t(n)) = \{L \subseteq \Sigma^* : L \text{ is decided by an } O(t(n))\text{-time single tape TM}\}$

Definition 4 (NTIME)

For $t: \mathbb{N} \rightarrow \mathbb{N}$, let $\text{NTIME}(t(n)) = \{L \subseteq \Sigma^* : L \text{ is decided by an } O(t(n))\text{-time single tape NTM}\}$

\mathcal{P} is the set of languages decidable in polynomial time on **deterministic** TMs.

Definition 5 (\mathcal{P})

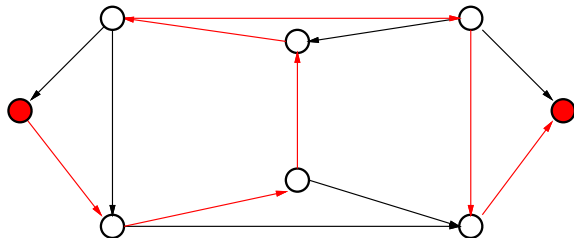
$$\mathcal{NP} = \bigcup_{c \geq 0} \text{DTIME}(n^c)$$

\mathcal{NP} is the set of languages decidable in polynomial time on **nondeterministic** TMs.

Definition 6 (\mathcal{NP})

$$\mathcal{NP} = \bigcup_{c \geq 0} \text{NTIME}(n^c)$$

Hamiltonian path



A **Hamiltonian path** in a directed G visits each node **exactly** once.

$$\text{HAMPATH} = \{ \langle G, s, t \rangle : G \text{ has Hamiltonian path from } s \text{ to } t \}$$

Question 7

How hard is it to decide **HAMPATH**?

Easy to obtain **exponential time** algorithm:

- ▶ Generate each potential path
- ▶ Check whether it is Hamiltonian

HAMPATH $\in \mathcal{NP}$

Here is an NTM that decides HAMPATH in polynomial time.

Algorithm 8 (N)

On input $\langle G = (V, E), s, t \rangle$,

1. **Guess** a list of numbers p_1, \dots, p_m , where $m = |V|$ and $1 \leq p_i \leq m$.
2. **Accept** if **all** the following hold (otherwise **Reject**):
 - ▶ No repetitions in list
 - ▶ $p_1 = s$ and $p_m = t$.
 - ▶ $(p_i, p_{i+1}) \in E$ for every $1 \leq i \leq m - 1$

- ▶ How does a TM **guess** a string?

Claim 9

N runs in polynomial time

Verifiability of HAMPATH

This problem has one very interesting feature: **polynomial verifiability**:

*We don't know a fast way to **find** a Hamiltonian path, but we can **check** whether a **given path** is Hamiltonian in polynomial time.*

Verifying correctness of a path is much **easier** than **determining** whether one exists

Section 2

Verifiability

Verifiability

Definition 10 (verifier)

A *deterministic* algorithm V is a **verifier** for a language L , if

▶ $x \in L \implies \exists c \in \{0, 1\}^*$ s.t. $V(x, c) = 1$.

▶ $x \notin L \implies \nexists c \in \Sigma^*$ s.t. $V(x, c) = 1$.

- ▶ The verifier uses the additional information c to verify $x \in L$.
- ▶ If V accepts (x, c) (i.e., outputs 1), the string c is called a **certificate** (also known as, **proof** or **witness**) for x .
- ▶ A **polynomial verifier** runs in polynomial time in $|x|$ (i.e., in the length of its **left-hand-side** input parameter).
- ▶ A language L is **polynomially verifiable**, if it has a polynomial verifier.
- ▶ A certificate for $\langle G, s, t \rangle \in \text{HAMPATH}$ is simply the Hamiltonian path from s to t .

Easy to **verify** in time polynomial in $|\langle G, s, t \rangle|$ whether given path is Hamiltonian.

- ▶ **Not** all languages are known to be polynomially verifiable.

NP and Verifiability

Theorem 11

A language is in \mathcal{NP} iff it has a *polynomial time verifier*.

Proof's idea:

- ▶ The NTM emulates the verifier by guessing the certificate.
- ▶ Verifier emulates NTM by using accepting branch as certificate.

Verifiability $\implies \mathcal{NP}$

Claim 12

If L has a poly-time verifier, then it is decided by some polynomial-time NTM.

Proof: Let V be poly-time verifier for L of running time $p(n)$ for some $p \in \text{poly}$.

Algorithm 13 (N)

On input $x \in \{0, 1\}^n$:

1. **Guess** a string c of length $p(n)$.
2. Emulate V on $\langle x, c \rangle$
3. **Accept** if V accepts; Otherwise **Reject**.



- ▶ Why is it suffices to guess a string of length $p(n)$?

$\mathcal{NP} \implies$ Verifiability

Claim 14

If L is decided by a polynomial-time NTM N , then L has a poly-time verifier.

Proof: Assume for simplicity that at each step of N , the number of possible non-deterministic moves is at most two.

Algorithm 15 (V)

On input (x, c) :

1. Emulate $N(x)$, treating each symbol of c as a description of the non-deterministic choice in each step of N .
2. **Accept** if this branch accepts; Otherwise **Reject**.

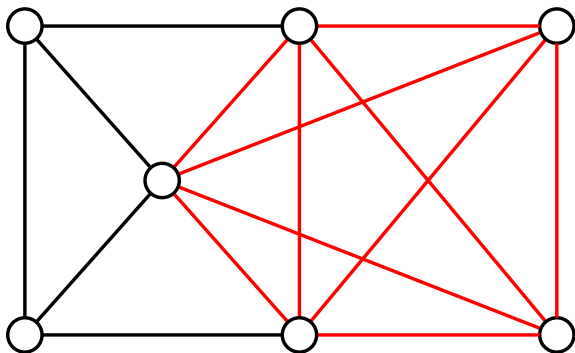


Without the simplifying assumption?

Section 3

A few more NP languages

CLIQUE



A **clique** in a graph is a subgraph where every two nodes are connected by an edge.

A **k -clique** is a clique of size k .

Question 16

What is the **largest k -clique** in the figure?

CLIQUE cont.

$\text{CLIQUE} = \{ \langle G, k \rangle : G \text{ is an undirected graph with a } k\text{-clique} \}$

Theorem 17

$\text{CLIQUE} \in \mathcal{NP}$

Proof's idea: The clique is the certificate.

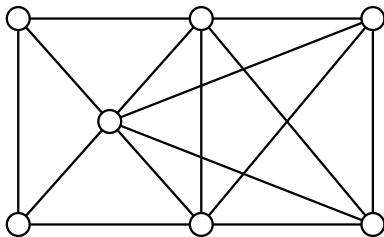
Algorithm 18 (V)

On input $(\langle G, k \rangle, c)$

Accept if c is a k -clique subgraph of G ;

Otherwise Reject.

Independent set



An **independent set** in a graph is a set of vertexes, no two of which are linked by an edge.

A **k -IS** is an independent set of size k .

Question 19

What is the **largest k -IS** in the figure?

Independent set cont.

$\text{IND-SET} = \{\langle G, k \rangle : G \text{ contains an independent set of size } k\}$

Theorem 20

$\text{IND-SET} \in \mathcal{NP}$

Proof's idea: The independent set is the certificate.

Algorithm 21 (V)

On input $(\langle G, k \rangle, c)$

Accept if c is a k -IS of G (no edges between nodes in c , and $|c| = k$);

Otherwise Reject.

Section 4

co-NP

The class co-NP

$\overline{\text{CLIQUE}} = \{\langle G, k \rangle : G \text{ is an undirected graph with no } k\text{-clique}\}$ seems **not** to be member of NP .

It seems harder to efficiently verify that something does **not** exist than to efficiently verify that something **does** exist.

Definition 22 (co-NP)

$\text{co-NP} = \{L : \bar{L} \in \text{NP}\}$.

But.. we are not sure...So far, **no one** knows if co-NP is distinct from NP .

Claim 23

$\mathcal{P} \subseteq \text{co-NP}$.

Proof? $L \in \mathcal{P} \implies \bar{L} \in \mathcal{P} \implies \bar{L} \in \text{NP} \implies L \in \text{co-NP}$.

Is Primality in NP ? co-NP ?

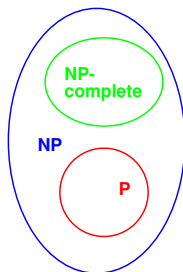
How would you prove that a number is prime without trying all divisors?

Actually it is in P! (not obvious at all)

Section 5

NP Completeness

NP Completeness



The class of **NP-complete** languages are

- ▶ “hardest” languages in \mathcal{NP}
- ▶ If any NP-complete $L \in P$, then $\mathcal{NP} = P$.

Question 24

Are there NP-complete languages?

Polynomial-time reducibility

Definition 25 (poly-time computable functions)

A function $f : \Sigma^* \rightarrow \Sigma^*$ is **polynomial-time computable**, if there is a poly-time **deterministic** TM that

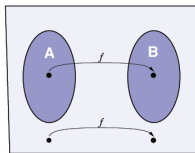
- ▶ starts with input w , and
- ▶ halts with $f(w)$ on tape.

Definition 26 (poly-time reduction)

A polynomial-time computable $f : \Sigma^* \rightarrow \Sigma^*$ is a **poly-time reduction** from language A to B , if $x \in A \iff f(x) \in B$ for every $x \in \Sigma^*$.

Is such a reduction from A to B exists, we say that A is **poly-time mapping reducible** to B , denoted $A \leq_P B$.

The mapping f **efficiently** converts questions about membership in A to membership in B .



Example: CLIQUE \leq_P IND-SET

Proof:

Definition 27

The **complement** of a graph $G = (V, E)$ is a graph $G^c = (V, E^c)$, where $E^c = \{(v_1, v_2) : v_1, v_2 \in V \text{ and } (v_1, v_2) \notin E\}$.

The reduction $f(G, k)$ from CLIQUE to IND-SET simply computes the complement of the graph and outputs (G^c, k) .

f satisfies:

- ▶ U is a **clique** in G \iff U is a **independent set** in G^c .
- ▶ computable in polynomial time!



Remark 28

Same reduction shows that IND-SET \leq_P CLIQUE

Reductions to \mathcal{P}

Theorem 29

If $A \leq_P B$ and $B \in \mathcal{P}$ then $A \in \mathcal{P}$.

Proof:

- ▶ Let f the reduction from A to B , computed by TM M_f .
On input x , the TM M_f makes at most $c_f \cdot |x|^{a_f}$ steps.
- ▶ Let M_B be the poly-time decider for B .
On input y , the TM M_B makes at most $c_B \cdot |y|^{a_B}$ steps.

Algorithm 30 (Decider M_A for A)

On input x , return $M_B(f(x))$

- ▶ M_A decides A
- ▶ Since $|f(x)| \leq c_f |x|^{a_f}$, running time of $M_B(x)$, is at most $c_B \cdot (c_f \cdot |x|^{a_f})^{a_B} = (c_B \cdot c_f^{a_B}) \cdot |x|^{a_f \cdot a_B} \in \text{poly}(|x|)$
Hence, $A \in \mathcal{P}$

What $A \leq_P B$ tells us about B?

Question 31

Assume that $\{0^n 1^n : n \geq 0\} \leq_P L$. Does it yield that $L \in \mathcal{P}$?

Answer: No. (Reduction in the wrong direction!)

Let $L = H_{TM, \varepsilon}$ and define $f(x) = \begin{cases} M_{stop}, & x \in \{0^n 1^n : n \in \mathbb{N}\} \\ M_{no-stop}, & \text{otherwise.} \end{cases}$

$A \leq_P B$ does tell us that B is “at least as hard” as A.

NP completeness, formal definition

Definition 32 (\mathcal{NP} -complete)

A language B is **NP-complete**, if

- ▶ $B \in \mathcal{NP}$, and
- ▶ Every $A \in \mathcal{NP}$ is **poly-time** reducible to B (i.e., $A \leq_P B$)

Let \mathcal{NPC} denote the class of all \mathcal{NP} -complete languages.

Compare to

Definition 33 (RE-complete)

A language B is **RE-complete**, if

- ▶ $B \in \mathcal{RE}$, and
- ▶ Every $A \in \mathcal{RE}$ is **mapping** reducible to B .

Why NP completeness?

Theorem 34

If $B \in \mathcal{NPC}$ and $B \in \mathcal{P}$, then $\mathcal{P} = \mathcal{NP}$.

Proof: Immediately follows by **Thm 29**. ♣

To show $\mathcal{P} = \mathcal{NP}$, it suffices to find a polynomial-time algorithm for **any** NP-complete problem.

We would like to find an $L \in \mathcal{NPC}$ that is “**natural**” and “**easy**” to reduce to.

Section 6

Satisfiability

Boolean variables

- ▶ A **Boolean** variable assumes values
 - ▶ **TRUE** (written **1**), and **FALSE** (written **0**).
- ▶ Boolean operations:
 - ▶ and: \wedge
 - ▶ or: \vee
 - ▶ not: \neg
- ▶ Examples:

$$0 \wedge 1 = 0$$

$$0 \vee 1 = 1$$

$$\overline{0} = 1$$

Boolean formulas and SAT

A **Boolean** formula is an expression involving Boolean variables and operations.

$$\phi = (\bar{x} \wedge y) \vee (x \wedge \bar{z})$$

Definition 35 (satisfiable formula)

A formula is **satisfiable**, if some **Boolean** assignment to its variables, makes the formula evaluate to **1**.

The formula $\phi = (\bar{x} \wedge y) \vee (x \wedge \bar{z})$ is satisfiable by the assignment

$$x = 0$$

$$y = 1$$

$$z = 0$$

The language of satisfied formulas:

$$\text{SAT} = \{\langle \phi \rangle : \phi \text{ is a satisfiable Boolean formula}\}$$

$SAT \in \mathcal{NP}$

$SAT = \{\langle \phi \rangle : \phi \text{ is satisfiable Boolean formula}\}$

Theorem 36 (Cook-Levin (early 70s))

$SAT \in \mathcal{NP}$.

- ▶ The “most important” \mathcal{NP} -complete language.
- ▶ It is easy to see that $SAT \in \mathcal{NP}$

Section 7

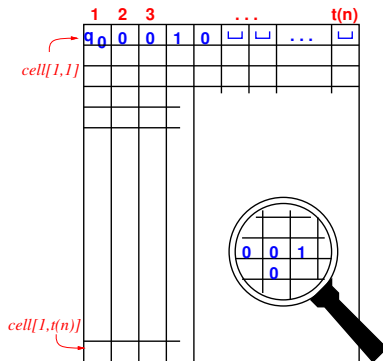
Proving $\text{SAT} \in \mathcal{NPC}$

The proof, high level

- ▶ Let $L \in \mathcal{NP}$ and let $N = (Q, \Sigma, \Gamma, \delta, q_0, q_a, q_r)$ be an t -time NTM that accepts L , for some $t \in \text{poly}$.
- ▶ Given the string $w \in \{0, 1\}^*$, construct in time $O(p(|w|)^2)$ a formula $\phi_{N,w}$ such that: $\phi_{N,w} \in \text{SAT}$ iff N accepts w .
- ▶ Hence, the mapping $w \rightarrow \phi_{N,w}$ is a poly-time reduction from L to SAT , establishing $L \leq_P \text{SAT}$.
- ▶ In the following fix L , N and $w \in \{0, 1\}^n$.
- ▶ We assume wlg. that $M(w)$ halts after exactly $t(n)$ steps.

The configuration-history Tableau

Consider the $t(n)$ -by- $t(n)$ Tableau that describes a possible accepting computation history of N on input w .



- ▶ First row represents initial configuration of N on input w .
- ▶ i 'th row represents the i -th configuration in a possible computation of N on input w .

The formula $\phi_{N,w}$

- ▶ Let $S = Q \cup \Gamma$ (the alphabet of the configuration history).
- ▶ $\phi_{N,w}$ uses Boolean variables $\{x_{i,j,s}\}_{i,j \in [t(n)], s \in S}$.

$$\phi_{N,w} = \phi_{\text{Cell}(N)} \wedge \phi_{\text{Start}(w)} \wedge \phi_{\text{Move}(N)} \wedge \phi_{\text{Accept}(N)}$$

- ▶ Given an assignment z for $\phi_{N,w}$, let $T(z)$ be the $t(n) \times t(n)$ Tableau, defined by setting the j -th cell in i 'th configuration to s , if $x_{i,j,s} = 1$ in z .
($T(z)$ is **undefined**, if $x_{i,j,s'} = x_{i,j,s} = 1$ for some $s \neq s' \in S$, or $x_{i,j,s} = 0$ for all $s \in S$).
- ▶ $T(z)$ will represent a (possible) **accepting execution** of $N(w)$, iff z is an **satisfying assignment** for $\phi_{N,w}$.

The formula $\phi_{\text{Cell}(N)}$

$\phi_{\text{Cell}(N)}$ guarantees that the variables encode **legal** configurations:

- ▶ Each cell (i, j) has at least one letter: $\bigvee_{s \in S} x_{i,j,s}$.
- ▶ No cell (i, j) has two or more letters $\bigwedge_{s \neq s' \in S} \overline{x_{i,j,s} \wedge x_{i,j,s'}}$.

Together:

$$\phi_{\text{Cell}(N)} = \bigwedge_{i,j} \left[\left(\bigvee_{s \in S} x_{i,j,s} \right) \wedge \left(\bigwedge_{s \neq s' \in S} \overline{x_{i,j,s} \wedge x_{i,j,s'}} \right) \right]$$

Claim 37

If an assignment z satisfies $\phi_{\text{Cell}(N)}$, then $T(z)$ is defined.

The formula $\phi_{\text{Start}(w)}$

$\phi_{\text{Start}(w)}$ guarantees that the first row encodes the initial configuration (i.e., $q_0 w$).

$$\begin{aligned}\phi_{\text{start}(w)} = & X_{1,1,q_0} \wedge X_{1,2,w_1} \wedge X_{1,3,w_2} \wedge \dots \wedge X_{1,n+1,w_n} \\ & \wedge X_{1,n+2,\sqcup} \wedge \dots \wedge X_{1,t(n),\sqcup}\end{aligned}$$

Claim 38

If z satisfies $\phi_{\text{Cell}(N)} \wedge \phi_{\text{Start}(w)}$, then the first line of $T(z)$ is $q_0 w \underbrace{\sqcup \dots \sqcup}_{t(n)-n-1}$.

The formula $\phi_{\text{Move}(N)}$

$\phi_{\text{Move}(N)}$ is the “heart” of $\phi_{N,w}$. To construct it, we employ **locality** of computations.

Observation: Configuration C , with head location h , yields configuration C' (with respect to δ), if the following holds.

- ▶ $C'_i = C_i$ for any $i \notin \{h-1, h, h+1\}$
- ▶ $C'_{h-1, h, h+1}$ is **consistent** (with respect to δ) with $C_{h-1, h, h+1}$.

We check that each configuration in $T(z)$ yields the next one, by inducing **local** “checks” on z .

$\phi_{\text{Move}(N)}$ – Rectangles

- ▶ A **rectangle** is a 2×3 configuration sub-table.
- ▶ Assume that $\delta(q_1, a) = \{(q_1, b, R)\}$ and $\delta(q_1, b) = \{(q_2, c, L), (q_2, a, R)\}$.
- ▶ (some) **Legal** 2×3 rectangles:

a	q_1	b
q_2	a	c

a	q_1	b
a	a	q_2

a	a	q_1
a	a	b

a	b	a
a	b	q_2

b	b	b
c	b	b

a	a	b
a	a	b

- ▶ (some) **Illegal** 2×3 rectangles:

a	b	a
a	a	a

a	q_1	b
q_1	a	a

b	q_1	b
q_2	b	q_2

- ▶ There is a **constant** number of legal rectangles (determined by δ).
- ▶ Denote this set by $C = C(\delta)$.

$\phi_{\text{Move}(N)}$ – Characterizing legal rectangles

The formula “verifies” that all 2×3 rectangles in the Tableau are in the list C :

1.

a	b	c
*	b	*

2.

a	q	b
q'	a	b'

a	q	b
a	b'	q'

$(L, q', b') \in \delta(q, b)$ $(R, q', b') \in \delta(q, b)$

3.

q	*	*
*	*	*

*	*	q
*	*	*

- Some rectangles in C are clearly illegal.
- For rectangles on the left-most and right-most side of Tableau, we use slightly different first type rectangles.

$\phi_{\text{Move}(N)}$ – formal definition

- ▶ For each entry $(i, j) \in [t(n)] \times [t(n)]$ and $c \in C$, let $\phi_{\text{Move},i,j,c}$ be the formula taking the value 1 iff the 2×3 table of cells in the Tableau whose upper-left corner is (i, j) is c .

For instance, for entry $(1, 1)$ and $c =$

a	q_1	b
q_2	a	d

let $\phi_{\text{Move},1,1,c} = x_{1,1,a} \wedge x_{1,2,q_1} \wedge x_{1,3,b} \wedge x_{2,1,q_2} \wedge x_{2,2,a} \wedge x_{2,3,d}$

- ▶ Finally, let $\phi_{\text{Move}(N)} = \bigwedge_{(i,j)} \bigvee_{c \in C} \phi_{\text{Move},i,j,c}$.

Claim 39

If z satisfies $\phi_{\text{Cell}(N)} \wedge \phi_{\text{Start}(w)} \wedge \phi_{\text{Move}(N)}$, then $T(z)$ is a **possible** configuration history of $N(w)$.

Proof: By induction on the row index. Base case: z satisfies $\phi_{\text{Cell}(N)} \wedge \phi_{\text{Start}(w)}$. Assume configuration defined in rows $1, \dots, i$ is possible and head is in cell j . The configuration of rows $1, \dots, i+1$ is also possible: Cells of indices **not** in $\{j-1, j, j+1\}$, by **first** type of rectangles in C . Other cells, by **second** type rectangles in C . **Q:** Why do we need the **third** type of cells?

The formula $\phi_{\text{Accept}(N)}$

$\phi_{\text{Accept}(N)}$ guarantees that some row encodes an accepting configuration (i.e., $uq_a v$):

$$\phi_{\text{Accept}(N)} = \bigvee_{i,j} x_{i,j,q_a}$$

Claim 40

If z satisfies $\phi_{N,w} = \phi_{\text{Cell}(N)} \wedge \phi_{\text{Start}(w)} \wedge \phi_{\text{Move}(N)} \wedge \phi_{\text{Accept}(N)}$, then $T(z)$ is an **accepting** configuration history of $N(w)$.

Correctness of reduction

- ▶ The transformation $w \rightarrow \phi_{N,w}$ is computable in time $O(n^{2c})$.
- ▶ An assignment satisfying $\phi_{N,w}$, corresponds to an **accepting** configuration history of $N(w)$.
- ▶ An **accepting** configuration history of $N(w)$ corresponds to an assignment satisfying $\phi_{N,w}$. (?)

Therefore, N accepts w iff $\phi_{N,w} \in \text{SAT}$.



- ▶ For complete details, consult Sipser chapter 7.4.