

Computational Models – Lecture 11¹

Nachum Dershowitz & Yishay Mansour

Tel Aviv University

June 2017

¹Based on foils by Iftach Haitner, Benny Chor, Maurice Herlihy.

Talk Outline

- ▶ Introduction to time complexity
 - ▶ The class \mathcal{P}
 - ▶ The class \mathcal{NP}
 - ▶ Verifiability
- Sipser 7.1-7.3

Part I

Introduction to Time Complexity

How long does it take to decide $L = \{0^n 1^n : n \geq 0\}$

Clearly $L \in \mathcal{R}$.

Question 1

How much time does a **single-tape** TM need to decide L ?

Algorithm 2 (Decider M_1 for L)

On input string w :

1. Scan across tape and **Reject** if **0** is found to the right of a **1**.
2. While both **0**s and **1**s appear on tape, repeat the following:
Scan across tape, crossing off a single **0** and a single **1** in each pass.
3. **Accept** if no **0**s and **1**s remain; otherwise **Reject**.

We analyze the time it takes to perform each of the three steps separately. In the following let $n = |w|$.

Analyzing Step 1

*Scan across tape and **Reject** if 0 is found to the right of a 1. If not, return to starting point.*

- ▶ Scanning requires n steps.
- ▶ Re-positioning head requires n steps.
- ▶ Total is $2n = O(n)$ steps.

Analyzing Step 2

While both 0s and 1s appear on tape, repeat the following

Scan across tape, crossing off a single 0 and a single 1 in each pass.

- ▶ Each scan requires $O(n)$ steps.
- ▶ Since each scan crosses off two symbols, the number of scans is at most $n/2$.
- ▶ Total number of steps is $(n/2) \cdot O(n) = O(n^2)$.

Analyzing Step 3

If 0s still remain after all 1s have been crossed out, or vice-versa, Reject. Otherwise, if the tape is empty, Accept.

- ▶ Single scan requires $O(n)$ steps.
- ▶ Total is $O(n)$ steps.

Overall cost

Total cost for the three steps

1. $O(n)$
2. $O(n^2)$
3. $O(n)$

which is $O(n^2)$

Deterministic Time

Definition 3 (Deterministic Time)

Let M be a **deterministic** TM, and let $t : \mathbb{N} \mapsto \mathbb{N}$. We say that M runs in time $t(n)$, if For **every** input x of length n , the number of steps that $M(x)$ uses is **at most** $t(n)$.

Question 4

What is a “step”?

Definition 5 (DTIME)

For $t : \mathbb{N} \mapsto \mathbb{N}$, let $\text{DTIME}(t(n)) =$
 $\{L \subseteq \Sigma^* : L \text{ is } \mathbf{decided} \text{ by an } O(t(n))\text{-time } \mathbf{single\ tape\ TM}\}$

Note that $t(n)$ running time, is also required for strings **not** in L .

Language Encoding

- ▶ Let $L = \{1^n : n \in \mathbb{N}\}$. (over Σ)
Is L in $\text{DTIME}(n)$? in $\text{DTIME}(n^{1/2})$? Proof?
- ▶ Let $\text{PATH} = \{\langle G, s, t \rangle : G \text{ has directed path from } s \text{ to } t\}$
Is L in $\text{DTIME}(n)$? in $\text{DTIME}(n^{1/2})$?
- ▶ The questions are **not well defined** w/o defining the **encoding** of strings into triplets $\langle G, s, t \rangle$.
- ▶ Encoding may matter **much** – an **exponential** algorithm with respect to one encoding might turn to **linear** algorithm with respect to other encoding.

If not defined explicitly, we assume a “reasonable encoding”:

- ▶ Graph encoding: **adjacency list** or **adjacency matrix**
- ▶ Integer encoding: **binary/decimal** encoding (and not **unary**)

Encoding of integers: binary versus unary

- ▶ Factorization algorithm
 1. Do for $i = 2$ to $q - 1$:
 - ★ If i divides q output i and halt.
 2. Output "none" and halt.
- ▶ What is the running time?
 - ▶ $O(q)$ (easily improved to $O(\sqrt{q})$)
 - ▶ Yay: poly(nomial) time! ? Yes, if q represented in unary.
 - ▶ Uh oh... number of bits to represent q in binary is $\log q$, so $O(q)$ is EXPONENTIAL IN THE INPUT LENGTH
- ▶ Today's crypto systems assume that factoring 4,000 bit numbers takes a long time!

Relations among time classes

Let $t_1, t_2 : \mathbb{N} \mapsto \mathbb{N}$ be two functions.

Claim 6

If $t_1(n) = O(t_2(n))$, then $\text{DTIME}(t_1(n)) \subseteq \text{DTIME}(t_2(n))$.

Stated informally, more time does **not hurt**. But does it actually **help**?

Would like to say “if $t_1(n) = o(t_2(n))$ then $\text{DTIME}(t_1(n)) \subsetneq \text{DTIME}(t_2(n))$ ”.

But this is what we can get:

Claim 7

(Assume that $t_1(n)$ and $t_2(n)$ are time constructible^a). If $t_1(n) \in O(t_2(n)/\log(n))$, then $\text{DTIME}(t_1(n)) \subsetneq \text{DTIME}(t_2(n))$.

^a t is **time constructible** if the function mapping 1^n to the binary representation of $t(n)$ is computable in time $O(t(n))$.

Informally, **sufficiently more time does help**

Proof omitted (take complexity course, or search for “time hierarchy theorem”)

Back to $L = \{0^n 1^n : n \geq 0\} \in \text{DTIME}(n^2)$

We have seen that $L \in \text{DTIME}(n^2)$. Can we do **faster**?

Algorithm 8 (Decider M_2 for L)

On input string w

1. Scan across tape and **Reject** if **0** is found to the right of a **1**.
2. Repeat the following while both **0**s and **1**s appear on tape:
 - 2.1 Scan across tape, checking whether total number of **0**s plus **1**s is even or odd. If odd, **Reject**.
 - 2.2 Scan across tape, crossing off every other **0** (starting with the first), and every other **1** (starting with the first) in each pass.
3. **Accept** if all string is crossed off; Otherwise **Reject**.

Example: $w = 0^{13}1^{13}$

Correctness?

- ▶ Let binary representation of number of 0's and 1's be $a_k \dots a_0$ and $b_\ell \dots b_0$ respectively.
- ▶ If total number of 0s plus 1s is even, they have same parity $\implies a_0 = b_0$.
- ▶ Crossing off every other 0 and 1 has same effect as “shift right” on binary representation.
- ▶ So, next iteration checks $a_1 = b_1 \dots$
- ▶ When finish, know that $a_i = b_i$ for all i !

Running time analysis of M_2

Algorithm 9 (Decider M_2 for L)

On input string w

1. Scan across tape and **Reject** if 0 is found to the right of a 1.
2. Repeat the following while both 0s and 1s appear on tape:
 - 2.1 Scan across tape, checking whether total number of 0s plus 1s is even or odd. If odd, **Reject**.
 - 2.2 Scan across tape, crossing off every other 0 (starting with the first), and every other 1 (starting with the first) in each pass.
3. **Accept** if all string is crossed off; Otherwise **Reject**.

- ▶ One pass in each step (1,2,3) takes $O(n)$ time.
- ▶ **Steps 1,3**: each executed once
- ▶ **Step 2** executed $1 + \log_2 n$ times
- ▶ Total for **Step 2** is $(1 + \log_2 n)O(n) = O(n \log n)$.
- ▶ Grand total: $O(n) + O(n \log n) = O(n \log n)$.

Further improvements, anybody?

Question 10

Can the running time be made $o(n \log n)$?

Answer: Not on a **single tape** TM...

Claim 11

$L \notin \text{DTIME}(o(n \log n))$ (i.e., $L \notin \text{DTIME}(g(n))$ for any $g(n) \in o(n \log n)$).

Hence, $\text{CFL} \not\subseteq \text{DTIME}(o(n \log n))$.

In contrast, regular languages $\subseteq \text{DTIME}(O(n))$. (?)

The proof of the claim is an immediate corollary of the following lemma.

Lemma 12 (pumping lemma for low-time TMs)

For every TM M of running time $t(n) \in o(n \log n)$, exists $\ell \in \mathbb{N}$ such that: every $w \in \mathcal{L} = \mathcal{L}(M)$ with $|w| \geq \ell$, can be written as $w = xyz$, $|y| > 0$ and $xy^i z \in \mathcal{L}$ for every $i \geq 0$.

A two-tape decider for $L = \{0^n 1^n : n \geq 0\}$

Algorithm 13 (Two-tape Decider M_3 for L)

On input string w :

1. Scan across tape and **Reject** if 0 is found to the right of a 1.
2. Scan across 0s to first 1, copying 0s to tape 2.
3. Scan across 1s on tape 1 until the end. For each 1, cross off a 0. If no 0s left, **Reject**.
4. If any 0s left, **Reject**; otherwise **Accept**.

Question 14

What is M_3 running time?

Complexity of deciding $L = \{0^n 1^n\}$

- ▶ Single-tape M_1 : $O(n^2)$.
- ▶ single-tape M_2 : $O(n \log n)$ (fastest possible!).

Hence $L \in \text{DTIME}(O(n \log n))$, but not in $\text{DTIME}(O(f(n)))$ for $f(n) \in o(n \log n)$

- ▶ Two-tape M_3 : $O(n)$.

Important difference between complexity and computability:

- ▶ Computability: all reasonable models **equivalent** (Church-Turing)
- ▶ Complexity: choice of model **does** affect running time.

Question 15

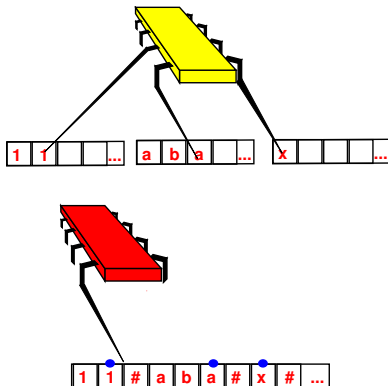
By **how much** does a model affect complexity?

Multitape speedup

Let $t(n)$ be a function where , and let $L \subseteq \Sigma^*$ be a language.

Claim 16

Assume $\exists t(n)$ -time multitape TM that decides L with $t(n) \geq n$, then \exists an $O(t(n)^2)$ -time single-tape TM that decides L .



Reminder: Emulating multitape TMs

Algorithm 17 (Single tape emulator S for k -tape M)

On input $w = w_1 \cdots w_n$:

1. Write $\# \overset{\bullet}{w}_1 w_2 \cdots w_n \# \overset{\bullet}{\sqcup} \# \overset{\bullet}{\sqcup} \# \cdots \#$ on tape.
 2. Scan tape from first $\#$ to $(k + 1)$ -st $\#$ to read symbols under virtual heads.
 3. Rescan tape to write new symbols and move heads.
 4. If need to move virtual head onto $\#$, shift tape content to the right.
- ▶ For each step of M , the emulator S performs 2 scans and up to k rightward shifts
 - ▶ On input of length n , M makes $O(t(n))$ many steps, so active portion of each tape is $O(t(n))$ long.
 - ▶ Total number of steps S makes:
 - ▶ $O(k \cdot t(n)) = O(t(n))$ steps to simulate **one step** of M .
 - ▶ Initial tape arrangement $O(n)$.
 - ▶ Grand total: $O(n) + O(t(n)^2) = O(t(n)^2)$ steps (recall $t(n) > n$).

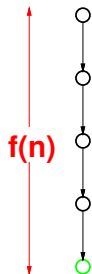
Non-deterministic time

Definition 18 (nondeterministic time)

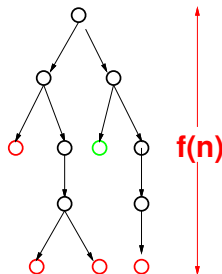
A **non-deterministic** TM N runs in time $f(n)$, where $f: \mathbb{N} \mapsto \mathbb{N}$, if for **every** input x of length n , the **maximum** number of steps that N uses on **any branch** of its computation tree on x , is **at most** $f(n)$.

Notice that also **non-accepting** branches must **reject** within $f(n)$ many steps.

deterministic



nondeterministic



TAKE NOTE: the **depth** of the tree, not the **size** of the tree!!!

Non-determinism speedup

Claim 19

Suppose N is a **nondeterministic** TM that runs in time $t(n)$ and decides the language L . Then there exists an $2^{O(t(n))}$ -time **deterministic** TM D that decides L .

Note contrast with multi-tape result.

Proof's idea: D emulates N . Reminder

- ▶ D tries all possible branches (say using BFS).
 - ▶ **Accept** if finds **any** accepting state.
 - ▶ **Reject** if **all** branches reject.
- ▶ Since N always stops, exactly one of two possibilities must occur.

Emulation details

We view the computation of N as a tree, whose nodes are configurations of the TM (i.e., state, head location and tape content).

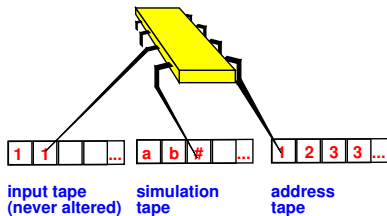
- ▶ Root is starting configuration,
- ▶ Fanout is at most some constant b (?),
- ▶ Depth at most $\leq t(n)$,
- ▶ Total number of nodes $O(b^{t(n)})$,
- ▶ Emulation time is $O(b^{t(n)}) = O(2^{O(t(n))})$

Remarks

1. Breadth-first search used in emulation

- ▶ Visit **each** node.
- ▶ May be improved upon by using depth-first search (**is it OK?**) or other tree search strategies.
- ▶ Still, doing this may save constants, but nothing substantial (?)

2. Simulation uses a three-tape machine.



Single-tape simulation: $(2^{O(t(n))})^2 = 2^{O(2t(n))} = 2^{O(t(n))}$.

Polynomial is faster than exponential

Assume one step takes $1/10^6$ fraction of a second....

	10	20	30	40	50	60
n	.00001 second	.00002 second	.00003 second	.00004 second	.00005 second	.00006 second
n^2	.0001 second	.00004 second	.00009 second	.00016 second	.00025 second	.00036 second
n^3	.001 second	.00008 second	.027 second	.064 second	.125 second	.216 second
n^5	.1 second	3.2 seconds	24.3 seconds	1.7 minute	5.2 minutes	13.0 minutes
2^n	.001 second	1.0 second	17.9 minutes	12.7 days	35.7 years	366 centuries
3^n	.059 second	58 minutes	6.5 years	3855 centuries	$2 \cdot 10^8$ centuries	$1.3 \cdot 10^{13}$ centuries

Exponential time factoring algorithms

2008 claim on forum:

1 hr for 120 bits
10 hrs for 150 bits
100 hrs for 180 bits
1000 hrs for 210 bits

Gaps between models

- ▶ At most **polynomial** gap in time to perform tasks between different deterministic models (single- vs. multi-tape TMs, TM vs. **RAM**, etc.)
- ▶ Apparently **exponential** gap in time to perform tasks between **deterministic** and **non-deterministic** models.

Claim 20

All “reasonable” classical (not including quantum) models of computation are polynomially equivalent.

Any one can simulate another with only **polynomial blowup** in running time.

Fact 21

Is a given problem solvable in

- ▶ *Linear time? **model-specific**.*
- ▶ *Polynomial time? **model-independent**.*

Part II

The Class P

The class \mathcal{P}

\mathcal{P} is the set of languages decidable in polynomial time on deterministic TMs.

Definition 22 (\mathcal{P})

$$\mathcal{P} = \bigcup_{c \geq 0} \text{DTIME}(n^c)$$

The class \mathcal{P} is important because:

- ▶ Invariant for all (deterministic) models of computation polynomially equivalent to TMs
 - ▶ not affected by particulars of model ...
 - ▶ go ahead, have another tape, they're pretty small and inexpensive
 - ...
- ▶ Roughly corresponds to **realistically solvable** (tractable) problems.
 - ▶ actually depends on context
 - ▶ going from exponential to polynomial algorithm usually requires major insight,
 - ▶ if you find an inefficient polynomial algorithm, you can often find a more efficient one.

Known problems in \mathcal{P}

- ▶ **Integer arithmetic:** Addition, subtraction, multiplication, division with remainder.
- ▶ **Modular arithmetic:** Exponentiation (RSA), inverse.
- ▶ **Integer Algorithms:** Greatest common divisor (gcd).
- ▶ **Operations research:** Maximum network flow, linear programming.
- ▶ **Algebra:** Matrix multiplication, computing determinants, matrix inversion, solving systems of linear equations, factoring polynomials.
- ▶ **Graph algorithms:** BFS and DFS in graphs, minimum spanning trees, finding Eulerian path.

PATH

$\text{PATH} = \{\langle G, s, t \rangle : G \text{ has directed path from } s \text{ to } t\}$

Theorem 23

$\text{PATH} \in \mathcal{P}$.

Algorithm 24 (M_1 – Naive algorithm for PATH)

Input: an m nodes graph G

For each path p in G of length $\leq m$: check if p goes from s to t .

Question 25

What is the (time) complexity of M_1 ?

- ▶ there are m^m possible paths
 - \implies exponential in number of nodes
 - \implies exponential in input size
- ▶ Oh, oh. Does not sound like \mathcal{P} to me ...

Efficient algorithm for PATH

Algorithm 26 (M_2 – efficient algorithm for PATH)

1. Place mark on s .
2. Repeat until no additional nodes marked:
 - 2.1 Scan edges of G .
 - 2.2 If edge (a, b) found from marked node a to unmarked node b , mark node b .
3. **Accept** if t is marked; otherwise **Reject**.

Question 27

What is the complexity of M_2 ?

- ▶ Steps 1 and 3 run once.
- ▶ Step 2 runs at most m times, because each time (except last) it marks at least one new node.

⇒ total number of steps is polynomial.

Relative primality

Two numbers are **relatively prime** if their *greater common divisor* (**gcd**) is 1 (i.e., the largest integer that divides them both).

- ▶ $\text{gcd}(10, 21) = 1 \implies 10$ and 21 **are** relatively prime
- ▶ $\text{gcd}(10, 22) = 2 \implies 10$ and 22 **are not** relatively prime

Definition 28

$\text{RELPRIME} = \{\langle x, y \rangle : \text{gcd}(x, y) = 1\}$.

Theorem 29

$\text{RELPRIME} \in \mathcal{P}$.

Naive algorithm for RELPRIME

Algorithm 30 (Naive algorithm for RELPRIME)

Input: integers x, y :

Search through all possible divisors of x, y and test divisibility.

- ▶ If x, y are give in **unary**:
 - ▶ Size of $\langle x \rangle$ is x
 - ▶ Testing all potential divisors of x, y is **polynomial**
- ▶ If x, y are give in **binary**
 - ▶ Size of $\langle x \rangle$ is $\log x$
 - ▶ Testing all potential divisors of x, y is **exponential**
- ▶ To analyze the running time of an algorithm that decides a language L , one should first say what is the **encoding** of L .
- ▶ Yet, we sometimes ignore that, and assume “reasonable encoding”
- ▶ The above algorithm is sometimes called **pseudo polynomial**.

Euclid's Algorithm for Computing gcd

Algorithm 31 (E)

On input $\langle x, y \rangle$:

1. Repeat until $x = 0$:
 - 1.1 If $y > x$, swap x and y .
 - 1.2 $x \leftarrow x \bmod y$
2. Output y .

Claim 32

E runs in polynomial-time and correctly computes the gcd function.

Algorithm 33 (M for RELPRIME)

On input $\langle x, y \rangle$:

Accept iff $E(x, y) = 1$.

To prove that RELPRIME $\in \mathcal{P}$, we only need to prove Claim 32.

Analyzing Euclid's algorithm

We will only prove the running time part.

Algorithm 34 (E)

On input $\langle x, y \rangle$:

1. Repeat until $x = 0$:

1.1 If $y > x$, swap x and y .

1.2 $x \leftarrow x \bmod y$

2. Output y .

- ▶ Each execution of Step 1.1 cuts x by at least half (case analysis for $y < x/2$ and $x/2 \leq y < x$)
- ▶ After each two executions maximal value is cut in half
 \implies number of stages is $\min(\log_2 x, \log_2 y) \implies$ total running time is polynomial.

Consequently, $\text{RELPRIME} \in \mathcal{P}$.



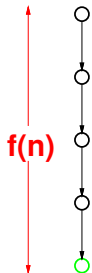
Non-deterministic time

Definition 35 (nondeterministic time)

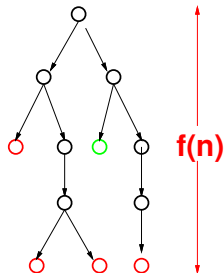
A **non-deterministic** TM N runs in time $f(n)$, where $f: \mathbb{N} \rightarrow \mathbb{N}$, if for **every** input x of length n , the **maximum** number of steps that N uses on **any branch** of its computation tree on x , is **at most** $f(n)$.

Notice that also **non-accepting** branches must **reject** within $f(n)$ many steps.

deterministic



nondeterministic



TAKE NOTE: the **depth** of the tree, not the **size** of the tree!!!

Part III

The Class NP

The Class \mathcal{NP}

Definition 36 (NTIME)

For $t: \mathbb{N} \rightarrow \mathbb{N}$, let $\text{NTIME}(t(n)) = \{L \subseteq \Sigma^* : L \text{ is decided by an } O(t(n))\text{-time single tape NTM}\}$

\mathcal{NP} is the set of languages decidable in polynomial time on non-deterministic TMs.

Definition 37 (\mathcal{NP})

$$\mathcal{NP} = \bigcup_{c \geq 0} \text{NTIME}(n^c)$$

The class \mathcal{NP} is important because:

- ▶ **Insensitive** to choice of reasonable non-deterministic computational model.
- ▶ Roughly corresponds to problems whose **positive solutions** are efficiently **verified**.

Are language in \mathcal{NP} decidable in polynomial time?

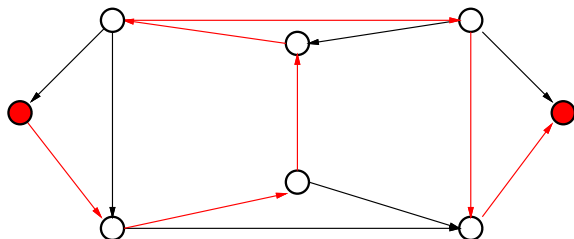
We don't know!

but what we do know is this:

Large class of fundamental languages in \mathcal{NP} that are “the hardest”

(i.e., if ONE is efficiently solvable then ALL are efficiently solvable)

Hamiltonian path



A **Hamiltonian path** in a directed G visits each node **exactly** once.

$$\text{HAMPATH} = \{ \langle G, s, t \rangle : G \text{ has Hamiltonian path from } s \text{ to } t \}$$

Question 38

How hard is it to decide **HAMPATH**?

Easy to obtain **exponential time** algorithm:

- ▶ Generate each potential path
- ▶ Check whether it is Hamiltonian

HAMPATH $\in \mathcal{NP}$

Here is an NTM that decides HAMPATH in polynomial time.

Algorithm 39 (N)

On input $\langle G = (V, E), s, t \rangle$,

1. **Guess** a list of numbers p_1, \dots, p_m , where $m = |V|$ and $1 \leq p_i \leq m$.
2. **Accept** if **all** the following hold (otherwise **Reject**):
 - ▶ No repetitions in list
 - ▶ $p_1 = s$ and $p_m = t$.
 - ▶ $(p_i, p_{i+1}) \in E$ for every $1 \leq i \leq m - 1$

- ▶ How does a TM **guess** a string?

Claim 40

N runs in polynomial time

Verifiability of HAMPATH

This problem has one very interesting feature: **polynomial verifiability**:

*We don't know a fast way to **find** a Hamiltonian path, but we can **check** whether a **given path** is Hamiltonian in polynomial time.*

Verifying correctness of a path is much **easier** than **determining** whether one exists

Verifiability

Definition 41 (verifier)

A *deterministic* algorithm V is a **verifier** for a language L , if

▶ $x \in L \implies \exists c \in \{0, 1\}^*$ s.t. $V(x, c) = 1$.

▶ $x \notin L \implies \nexists c \in \Sigma^*$ s.t. $V(x, c) = 1$.

- ▶ The verifier uses the additional information c to verify $x \in L$.
- ▶ If V accepts (x, c) (i.e., outputs 1), the string c is called a **certificate** (also known as, **proof** or **witness**) for x .
- ▶ A **polynomial verifier** runs in polynomial time in $|x|$ (i.e., in the length of its **left-hand-side** input parameter).
- ▶ A language L is **polynomially verifiable**, if it has a polynomial verifier.
- ▶ A certificate for $\langle G, s, t \rangle \in \text{HAMPATH}$ is simply the Hamiltonian path from s to t .

Easy to **verify** in time polynomial in $|\langle G, s, t \rangle|$ whether given path is Hamiltonian.

- ▶ **Not** all languages are known to be polynomially verifiable.

NP and Verifiability

Theorem 42

A language is in \mathcal{NP} iff it has a *polynomial time verifier*.

Proof's idea:

- ▶ The NTM emulates the verifier by guessing the certificate.
- ▶ Verifier emulates NTM by using accepting branch as certificate.

Verifiability $\implies \mathcal{NP}$

Claim 43

If L has a poly-time verifier, then it is decided by some polynomial-time NTM.

Proof: Let V be poly-time verifier for L of running time $p(n)$ for some $p \in \text{poly}$.

Algorithm 44 (N)

On input $x \in \{0, 1\}^n$:

1. **Guess** a string c of length $p(n)$.
2. Emulate V on $\langle x, c \rangle$
3. **Accept** if V accepts; Otherwise **Reject**.



- ▶ Why is it suffices to guess a string of length $p(n)$?

$\mathcal{NP} \implies$ Verifiability

Claim 45

If L is decided by a polynomial-time NTM N , then L has a poly-time verifier.

Proof: Assume for simplicity that at each step of N , the number of possible non-deterministic moves is at most two.

Algorithm 46 (V)

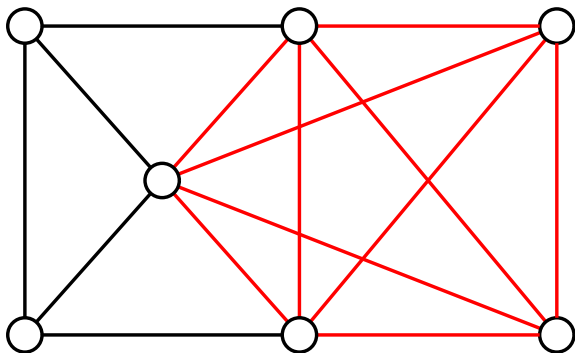
On input (x, c) :

1. Emulate $N(x)$, treating each symbol of c as a description of the non-deterministic choice in each step of N .
2. **Accept** if this branch accepts; Otherwise **Reject**.



Without the simplifying assumption?

CLIQUE



A **clique** in a graph is a subgraph where every two nodes are connected by an edge.

A **k -clique** is a clique of size k .

Question 47

What is the **largest k -clique** in the figure?

CLIQUE cont.

$\text{CLIQUE} = \{ \langle G, k \rangle : G \text{ is an undirected graph with a } k\text{-clique} \}$

Theorem 48

$\text{CLIQUE} \in \mathcal{NP}$

Proof's idea: The clique is the certificate.

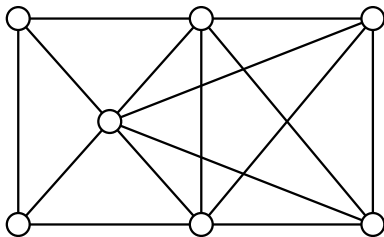
Algorithm 49 (V)

On input $(\langle G, k \rangle, c)$

Accept if c is a k -clique subgraph of G ;

Otherwise Reject.

Independent set



An **independent set** in a graph is a set of vertexes, no two of which are linked by an edge.

A **k -IS** is an independent set of size k .

Question 50

What is the **largest k -IS** in the figure?

Independent set cont.

$\text{IND-SET} = \{\langle G, k \rangle : G \text{ contains an independent set of size } k\}$

Theorem 51

$\text{IND-SET} \in \mathcal{NP}$

Proof's idea: The independent set is the certificate.

Algorithm 52 (V)

On input $(\langle G, k \rangle, c)$

Accept if c is a k -IS of G (no edges between nodes in c , and $|c| = k$);

Otherwise Reject.

The class co-NP

$\overline{\text{CLIQUE}} = \{\langle G, k \rangle : G \text{ is an undirected graph with no } k\text{-clique}\}$ seems **not** to be member of NP .

It seems harder to efficiently verify that something does **not** exist than to efficiently verify that something **does** exist.

Definition 53 (co-NP)

$$\text{co-NP} = \{L : \bar{L} \in \text{NP}\}.$$

But.. we are not sure...So far, **no one** knows if co-NP is distinct from NP .

Claim 54

$$\mathcal{P} \subseteq \text{co-NP}.$$

Proof? $L \in \mathcal{P} \implies \bar{L} \in \mathcal{P} \implies \bar{L} \in \text{NP} \implies L \in \text{co-NP}$.

Is Primality in NP ? co-NP ?

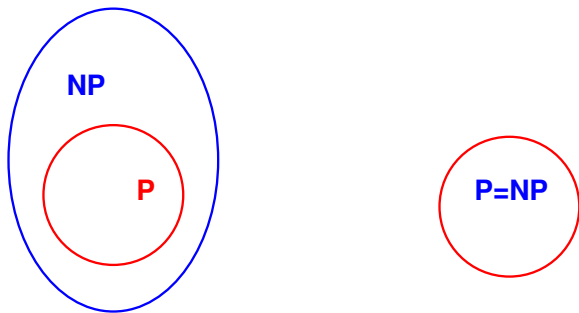
How would you prove that a number is prime without trying all divisors?

Actually it is in P! (not obvious at all)

Part IV

P vs. NP

\mathcal{P} vs. \mathcal{NP}



The question $\mathcal{P} \stackrel{?}{=} \mathcal{NP}$ is one of the great unsolved mysteries in contemporary mathematics.

P vs. NP

- ▶ Most computer scientists believe the two classes are **not** equal
- ▶ Leading computer scientists are not so sure
- ▶ Most bogus proofs show them equal (?)
- ▶ One of 7 Clay Millenium Prize problems (\$1,000,000!)
- ▶ “Computer Science’s greatest intellectual export” (Papadimitriou 2007)

\mathcal{P} Vs. \mathcal{NP} , cont.

If \mathcal{P} differs from \mathcal{NP} , then the distinction between \mathcal{P} and $\mathcal{NP} \setminus \mathcal{P}$ is meaningful and important.

- ▶ languages in \mathcal{P} are **tractable**
- ▶ languages in $\mathcal{NP} \setminus \mathcal{P}$ are **intractable**

Until we can prove that $\mathcal{P} \neq \mathcal{NP}$, there is no hope of proving that a **specific** language lies in $\mathcal{NP} \setminus \mathcal{P}$.

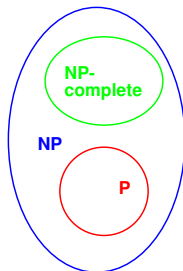
Nevertheless, we **can** prove statements of the form

If $A \in \mathcal{NP} \setminus \mathcal{P}$, then $B \in \mathcal{NP} \setminus \mathcal{P}$.

Part V

NP Completeness

NP Completeness



The class of **NP-complete** languages are

- ▶ “hardest” languages in \mathcal{NP}
- ▶ If any NP-complete $L \in P$, then $\mathcal{NP} = P$.

Question 55

Are there NP-complete languages?

Polynomial-time reducibility

Definition 56 (poly-time computable functions)

A function $f : \Sigma^* \rightarrow \Sigma^*$ is **polynomial-time computable**, if there is a poly-time **deterministic** TM that

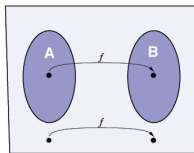
- ▶ starts with input w , and
- ▶ halts with $f(w)$ on tape.

Definition 57 (poly-time reduction)

A polynomial-time computable $f : \Sigma^* \rightarrow \Sigma^*$ is a **poly-time reduction** from language A to B , if $x \in A \iff f(x) \in B$ for every $x \in \Sigma^*$.

Is such a reduction from A to B exists, we say that A is **poly-time mapping reducible** to B , denoted $A \leq_P B$.

The mapping f **efficiently** converts questions about membership in A to membership in B .



Example: $\text{CLIQUE} \leq_P \text{IND-SET}$

Proof:

Definition 58

The **complement** of a graph $G = (V, E)$ is a graph $G^c = (V, E^c)$, where $E^c = \{(v_1, v_2) : v_1, v_2 \in V \text{ and } (v_1, v_2) \notin E\}$.

The reduction $f(G, k)$ from **CLIQUE** to **IND-SET** simply computes the complement of the graph and outputs (G^c, k) .

f satisfies:

- ▶ U is a **clique** in $G \iff U$ is a **independent set** in G^c .
- ▶ computable in polynomial time!



Remark 59

Same reduction shows that $\text{IND-SET} \leq_P \text{CLIQUE}$

Reductions to \mathcal{P}

Theorem 60

If $A \leq_P B$ and $B \in \mathcal{P}$ then $A \in \mathcal{P}$.

Proof:

- ▶ Let f the reduction from A to B , computed by TM M_f .
On input x , the TM M_f makes at most $c_f \cdot |x|^{a_f}$ steps.
- ▶ Let M_B be the poly-time decider for B .
On input y , the TM M_B makes at most $c_B \cdot |y|^{a_B}$ steps.

Algorithm 61 (Decider M_A for A)

On input x , return $M_B(f(x))$

- ▶ M_A decides A
- ▶ Since $|f(x)| \leq c_f |x|^{a_f}$, running time of $M_B(x)$, is at most $c_B \cdot (c_f \cdot |x|^{a_f})^{a_B} = (c_B \cdot c_f^{a_B}) \cdot |x|^{a_f \cdot a_B} \in \text{poly}(|x|)$
Hence, $A \in \mathcal{P}$

What $A \leq_P B$ tells us about B?

Question 62

Assume that $\{0^n 1^n : n \geq 0\} \leq_P L$. Does it yield that $L \in \mathcal{P}$?

Answer: No. (Reduction in the wrong direction!)

Let $L = H_{TM, \varepsilon}$ and define $f(x) = \begin{cases} M_{stop}, & x \in \{0^n 1^n : n \in \mathbb{N}\} \\ M_{no-stop}, & \text{otherwise.} \end{cases}$

$A \leq_P B$ does tell us that B is “at least as hard” as A.

NP completeness, formal definition

Definition 63 (\mathcal{NP} -complete)

A language B is **NP-complete**, if

- ▶ $B \in \mathcal{NP}$, and
- ▶ Every $A \in \mathcal{NP}$ is **poly-time** reducible to B (i.e., $A \leq_P B$)

Let \mathcal{NPC} denote the class of all \mathcal{NP} -complete languages.

Compare to

Definition 64 (RE-complete)

A language B is **RE-complete**, if

- ▶ $B \in \mathcal{RE}$, and
- ▶ Every $A \in \mathcal{RE}$ is **mapping** reducible to B .

Why NP completeness?

Theorem 65

If $B \in \mathcal{NPC}$ and $B \in \mathcal{P}$, then $\mathcal{P} = \mathcal{NP}$.

Proof: Immediately follows by **Thm 63**. ♣

To show $\mathcal{P} = \mathcal{NP}$ (and make an instant fortune, see www.claymath.org/millennium/P_vs_NP/), suffices to find a polynomial-time algorithm for **any** NP-complete problem.

Question 66

Is \mathcal{NPC} empty?

\mathcal{NPC} is not empty

$A_{NP} = \{ \langle M, x, 1^n \rangle : M \text{ is a TM} \wedge \exists c \in \Sigma^* \text{ s.t. } M(x, c) \text{ accepts within } n \text{ steps} \}$.

Theorem 67

$A_{NP} \in \mathcal{NP}$

Proof:

- ▶ Clearly $A_{NP} \in \mathcal{NP}$.
- ▶ Let $L \in \mathcal{NP}$, let V be a verifier for L and let $p \in \text{poly}$ be a bound on the running time of V (i.e., $V(x, \cdot)$ halts within $p(|x|)$ steps, for every $x \in \Sigma^*$).
- ▶ Define $f(x) = \langle V, x, 1^{p(|x|)} \rangle$.
- ▶ f is poly-time computable
- ▶ $x \in L \iff f(x) \in A_{NP}$.



Finding additional NP-complete languages

Theorem 68

Assume that

1. $B \in \mathcal{NP}$
2. $A \in \mathcal{NPC}$ and $A \leq_P B$

then $B \in \mathcal{NPC}$.

Proof: Home exercise ... ♣

We would like to find $L \in \mathcal{NPC}$ that is “natural” and “easy” to reduce to.